# Chapter 1 Exam Review: States and Operators

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## **Basics of States and Operators**

• Finite (e.g two component) systems, have a discrete number states, while other systems may have an infinite number. An orthonormal basis can be formed, any physical state of the system can be expressed as a linear combination of its members:

$$egin{aligned} &\langle\psi|=\sum_{i}a_{i}\left\langle i
ight|\ &|\psi
angle =\sum_{i}a_{i}^{st}\left|i
ight
angle \end{aligned}$$

- The bra notation is shown first. Ket adjoint vectors are their complex transposes.
- States are normalized to have unit squares:  $\langle \psi | \psi \rangle = \sum_{i} a_{i}^{*} a_{i} = 1$
- The squared overlap between two states gives the probability of observing a second state from an initial prepared state:

$$P = |\langle \psi | \phi \rangle |^2$$

• Operators act on functions/vectors to return transformed functions. We can express an operator in terms of its expectation for a pair of basis states:

$$A = \sum_{i,j} a_{i,j} \ket{i} ig\langle j 
vert$$

# **Basics of Two Component Systems**

• Consider the identity, and the Pauli matrices,  $\vec{\sigma} = (\sigma_x, \sigma_y, \sigma_z)$ :

$$\mathbb{1} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \sigma_x = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \sigma_y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}, \sigma_z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix},$$

• Together, the set forms a complete, unitary basis for the space of 2x2 matrices. This basis in commonly used to describe spinhalf systems (a two-component system in three space). Note,  $\sigma_i \sigma_j = \delta_{ij} + i\epsilon_{ijk}\sigma_k$ . Spin-up and spin-down states are expressed as:

$$\left|\uparrow\right\rangle = \begin{bmatrix}1\\0\end{bmatrix}, \left|\downarrow\right\rangle = \begin{bmatrix}0\\1\end{bmatrix}$$

• Rotations of such states in the spin-half system are expressed out by a Taylor expansion:

$$R(\vec{\theta}) = e^{-i\vec{\theta}\cdot\vec{\sigma}/2} = e^{-i\theta\hat{n}\cdot\vec{\sigma}/2} = \cos(\theta/2) - i\sin(\theta/2)\vec{\sigma}\cdot\hat{n}$$

- Alternately, rotations of two-component systems in two space can be expressed:
- One example of rotations in a 2D plane is the transformation of polarized fields about the direction of propagation (worth reviewing polarization naming conventions).

$$R(\phi) = \begin{bmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{bmatrix} = \cos \phi - i\sigma_y \sin \phi$$

# Example Problem 1: Two Component Neutrino Mixing

- A common application of two-state mixing is the atmospheric neutrino problem. Ground-based instruments have observed a deficit in the rate of muon neutrinos. As the rate of electron neutrinos was near expected,  $\nu_{\mu} \rightarrow \nu_{\tau}$  must occur.
- We can introduce a Hamiltonian for these two observed states, and add in an additional mixing term:

$$H = \begin{bmatrix} m_{\mu} & 0 \\ 0 & m_{\tau} \end{bmatrix} + \alpha \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

- This gives new Hamiltonian with different neutrino eigen-energies and eigen-states than those observed. What are these new eigen-energies, and probabilities  $P(numu \rightarrow nutau)$ ,  $P(numu \rightarrow numu)$ , as a function of time?
- Begin by expressing *H* in terms of Pauli matrices:

$$\begin{split} H &= \begin{bmatrix} m_{\mu} & \alpha \\ \alpha & m_{\tau} \end{bmatrix} \\ &= \alpha \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} m_{\mu} + m_{\tau} & 0 \\ 0 & m_{\mu} + m_{\tau} \end{bmatrix} + \frac{1}{2} \begin{bmatrix} m_{\mu} - m_{\tau} & 0 \\ 0 & m_{\tau} - m_{\mu} \end{bmatrix} \\ &= \alpha \sigma_x + \frac{1}{2} (m_{\mu} + m_{\tau}) \mathbb{1} + \frac{1}{2} (m_{\mu} - m_{\tau}) \sigma_z. \end{split}$$

• To diagonalize, 
$$\alpha \sigma_x + \frac{1}{2}(m_\mu + m_\tau)\mathbb{1} + \frac{1}{2}(m_\mu - m_\tau)\sigma_z$$
, note the triplet of Pauli matrices rotates as (x, y, x).

• Form an analogue vector of magnitude and direction from projections along the Pauli matrices:

$$eta = \sqrt{lpha^2 + (m_\mu - m_ au)^2/4} \ \hat{n} = (lpha, 0, (m_\mu - m_ au)/2)/eta \ H = rac{1}{2}(m_\mu + m_ au)\mathbbm{1} + eta(ec{\sigma}\cdot\hat{n})$$

• Scalar eigen-energies are maintained under the transformation/rotation of Pauli matrices. Rotating along the (diagonalized) z direction,

$$egin{aligned} H &= rac{1}{2}(m_{\mu}+m_{ au})\mathbb{1}+eta\sigma_{z} \ &= egin{bmatrix} (m_{\mu}+m_{ au})/2+eta & 0 \ 0 & (m_{\mu}+m_{ au})/2-eta \end{bmatrix}. \end{aligned}$$

• Can now read eigen-energies for the neutrino mass eigenstates from the diagonal.

- The evolution operator for time-independent Hamiltonians is,  $U=e^{-iHt/\hbar}$  :
- Unitary transformation, so basis is transformed but maintained as orthonormal.

$$U(t) = \exp\{-it(m_{\mu} + m_{\tau})\mathbb{1}/(2\hbar) - it\beta(\vec{\sigma} \cdot \hat{n})/\hbar\}$$
  
=  $\exp\{-it(m_{\mu} + m_{\tau})/(2\hbar)\}(\cos(\beta t/\hbar)\mathbb{1} - i\vec{\sigma} \cdot \hat{n}\sin(\beta t/\hbar))$   
=  $\exp\{-it(m_{\mu} + m_{\tau})/(2\hbar)\}(\cos(\beta t/\hbar)\mathbb{1} - (i/\beta)(\alpha\sigma_{x} + (m_{\mu} - m_{\tau})\sigma_{z}/2)\sin(\beta t/\hbar))\}$ 

• The probability of a specific oscillation is found by evolving the first state, and considering the squared projection onto the second:

$$\begin{aligned} \langle \nu_{\tau} | U(t) | \nu_{\mu} \rangle &= \begin{bmatrix} 0 & 1 \end{bmatrix} U(t) \begin{bmatrix} 1 \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} 0 & 1 \end{bmatrix} \exp\{-it(m_{\mu} + m_{\tau})/(2\hbar)\}(-(i/\beta)\alpha\sigma_{x}\sin(\beta t/\hbar)) \begin{bmatrix} 1 \\ 0 \end{bmatrix} \\ &= \exp\{-it(m_{\mu} + m_{\tau})/(2\hbar)\}(-(i/\beta)\alpha\sin(\beta t/\hbar)) \end{aligned}$$

• The expectation of observing numu after time **t** is found similarly.

$$P(\nu_{\mu} \to \nu_{\tau}) = \alpha^2 \sin^2(\beta t/\hbar)/\beta^2,$$
  

$$P(\nu_{\mu} \to \nu_{\mu}) = (m_{\mu} + m_{\tau})^2 \sin^2(\beta t/\hbar)/(4\beta^2) + \cos^2(\beta t/\hbar)$$

• Nice overview of two flavor neutrino oscillation formalism: https://warwick.ac.uk/fac/sci/physics/staff/academic/boyd/warwick\_week/neutrino\_physics/lec\_oscillations.pdf

## **Basics of Density Matrices**

• States can be described by a density matrix:

 $ho_\psi = |\psi
angle\langle\psi|$ 

• Density matrices are sufficient to generate all observables using:

$$egin{aligned} &\langle\psi|\mathcal{A}|\psi
angle &=\sum_{i,j}\psi_i^*A_{ij}\psi_j\ &=\operatorname{Tr}
ho_\psi\mathcal{A},\ &|\langle\phi|\mathcal{A}|\psi
angle|^2 =&<\psi|\mathcal{A}^\dagger|\phi
angle\langle\phi|\mathcal{A}|\psi
angle\ &=\operatorname{Tr}
ho_\psi\mathcal{A}^\dagger
ho_\phi\mathcal{A}. \end{aligned}$$

• The trace of any product of matrices is invariant to unitary transformations, so the formulas above work regardless of basis (see example problem)

# **Example Problem 2: Density Matrices**

#### Fall 1998 Final

1. (15 pt.s) Consider a spin 1/2 system. The projection operator  $P_z$  projects the component of the wave function that has positive spin along the z axis.

 $\langle \eta | P_z | \eta \rangle = |\langle z, \uparrow | \eta \rangle|^2$ 

- (a) Express  $P_z$  as a matrix in the basis where  $\begin{pmatrix} 1\\ 0 \end{pmatrix}$  denotes a state with positive spin along the z axis.
- (b) Write down the density matrix for a state that is an incoherent mixture of 50% positive spin along the y axis and 50% negative spin along the y axis.
- (c) If the Hamiltonian is defined as:

 $\mathcal{H} = \alpha + \beta \sigma_x$ 

Calculate the expectation of  $\mathcal{H}$  for the state described in b.

(a) Express  $P_z$  as a matrix in the basis where  $\begin{pmatrix} 1\\ 0 \end{pmatrix}$  denotes a state with positive spin along the z axis.

$$|z,\uparrow\rangle = \begin{pmatrix} 1\\0 \end{pmatrix} \qquad |z,\downarrow\rangle = \begin{pmatrix} 0\\1 \end{pmatrix}$$

$$P_{z} = |z,\uparrow\rangle\langle z,\uparrow| = \begin{pmatrix} 1\\0 \end{pmatrix} \begin{pmatrix} 1 & 0 \end{pmatrix}$$

$$P_{z} = \begin{pmatrix} 1 & 0\\0 & 0 \end{pmatrix}$$

$$P_{z} = \begin{pmatrix} 1 & 0\\0 & 0 \end{pmatrix}$$
Check:  $\langle \eta | P_{z} | \eta \rangle = |\langle z,\uparrow | \eta \rangle|$ 

$$|\eta\rangle = \begin{pmatrix} a\\b \end{pmatrix}$$

$$\langle \eta | P_{z} | \eta \rangle = (a \ b) \begin{pmatrix} 1 & 0\\0 & 0 \end{pmatrix} \begin{pmatrix} a\\b \end{pmatrix} = a^{2}$$

$$\langle z,\uparrow |\eta\rangle|^{2} = a^{2}$$

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(b) Write down the density matrix for a state that is an incoherent mixture of 50% positive spin along the y axis and 50% negative spin along the y axis.

$$\rho = \frac{1}{2} |y, \uparrow \rangle \langle y, \uparrow | + \frac{1}{2} |y, \downarrow \rangle \langle y, \downarrow$$

2 ways:

 $|y,\uparrow\rangle = \begin{pmatrix} 1\\0 \end{pmatrix} \qquad |y,\downarrow\rangle = \begin{pmatrix} 0\\1 \end{pmatrix}$   $\rho = \frac{1}{2} \begin{pmatrix} 1\\0 \end{pmatrix} \begin{pmatrix} 1&0 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 0\\1 \end{pmatrix} \begin{pmatrix} 0&1 \end{pmatrix}$   $\rho = \frac{1}{2} \begin{pmatrix} 1&0\\0&1 \end{pmatrix}$ 

$$|y,\uparrow\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1\\i \end{pmatrix} \qquad |y,\downarrow\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1\\-i \end{pmatrix}$$

$$\rho = \frac{1}{2} \cdot \frac{1}{2} \begin{pmatrix} 1\\i \end{pmatrix} (1 - i) + \frac{1}{2} \cdot \frac{1}{2} \begin{pmatrix} 1\\-i \end{pmatrix} (1 - i)$$

$$\rho = \frac{1}{4} \begin{pmatrix} 1&-i\\i & 1 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 1&i\\-i & 1 \end{pmatrix}$$

$$\rho = \frac{1}{4} \begin{pmatrix} 2&0\\0 & 2 \end{pmatrix}$$

$$\rho = \frac{1}{2} \begin{pmatrix} 1&0\\0 & 1 \end{pmatrix}$$

(c) If the Hamiltonian is defined as:

$$\mathcal{H} = \alpha + \beta \sigma_x$$

Calculate the expectation of  $\mathcal{H}$  for the state described in b.

Short way:  $\langle H \rangle = \operatorname{Tr}(\rho H)$   $\operatorname{Tr}(\rho H) = \alpha \operatorname{Tr}(\rho) + \beta \operatorname{Tr}(\rho \sigma_x)$   $\operatorname{Tr}(\rho H) = \alpha + \frac{\beta}{2} \operatorname{Tr}(\sigma_x)$  $\sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ 

$$\langle H\rangle = \alpha$$

(c) If the Hamiltonian is defined as:

$$\mathcal{H} = \alpha + \beta \sigma_x$$

Calculate the expectation of  $\mathcal{H}$  for the state described in b.

Long way:

$$H = \begin{pmatrix} \alpha & 0 \\ 0 & \alpha \end{pmatrix} + \begin{pmatrix} 0 & \beta \\ \beta & 0 \end{pmatrix} = \begin{pmatrix} \alpha & \beta \\ \beta & \alpha \end{pmatrix}$$
$$\langle H \rangle = \frac{1}{2} \langle y, \uparrow | H | y, \uparrow \rangle + \frac{1}{2} \langle y, \downarrow | H | y, \downarrow \rangle |$$
$$\langle H \rangle = \frac{1}{4} \begin{pmatrix} 1 & -i \end{pmatrix} \begin{pmatrix} \alpha & \beta \\ \beta & \alpha \end{pmatrix} \begin{pmatrix} 1 \\ i \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 1 & i \end{pmatrix} \begin{pmatrix} \alpha & \beta \\ \beta & \alpha \end{pmatrix} \begin{pmatrix} 1 \\ -i \end{pmatrix}$$
$$\langle H \rangle = \frac{1}{4} \begin{pmatrix} 1 & -i \end{pmatrix} \begin{pmatrix} \alpha + i\beta \\ \beta + i\alpha \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 1 & i \end{pmatrix} \begin{pmatrix} \alpha - i\beta \\ \beta - i\alpha \end{pmatrix}$$
$$\langle H \rangle = \frac{1}{2} \alpha + \frac{1}{2} \alpha$$