# Wigner-Eckart Theorem 

Jared De Chant and Artemis Tsantiri

April 2021

## Subject Exam August 2020 problem 2

A system of $\boldsymbol{N}$ spinless particles are self-bound due to an attractive radially symmetric interaction. States are labeled $|\boldsymbol{\alpha}, \boldsymbol{L}, \boldsymbol{M}\rangle$, where $\boldsymbol{L}$ and $\boldsymbol{M}$ reference the total angular momentum and $\boldsymbol{\alpha}$ accounts for all other quantum labels.
(i) (10 pts) For the matrix elements listed below, circle the NON-ZERO elements: ( $\boldsymbol{J}, \boldsymbol{R}, \boldsymbol{P}$ are current, position and momentum operators)

- $\left\langle\alpha^{\prime}, L^{\prime}=2, M^{\prime}=1\right| P_{x}^{2}+P_{y}^{2}|\alpha, L=4, M=3\rangle$
- $\left\langle\alpha^{\prime}, L^{\prime}=2, M^{\prime}=1\right| P_{x} P_{y}|\alpha, L=4, M=1\rangle$
- $\left\langle\alpha^{\prime}, L^{\prime}=2, M^{\prime}=1\right| \epsilon_{i j k} J_{i} R_{j} P_{k}|\alpha, L=2, M=1\rangle$
- $\left\langle\alpha^{\prime}, L^{\prime}=2, M^{\prime}=1\right| P_{x}|\alpha, L=4, M=3\rangle$
(ii) (10 pts) With great effort, you calculated the matrix element

$$
\mathcal{M}=\left\langle\alpha^{\prime}, L^{\prime}=2, M^{\prime}=0\right| P_{x}^{2}+P_{y}^{2}-2 P_{z}^{2}|\alpha, L=4, M=0\rangle
$$

by performing a long and difficult integral. If you were to use the Wigner-Eckart theorem, circle the matrix elements below you could express in terms of $\boldsymbol{\mathcal { M }}$ and Clebsch-Gordan coefficients without having to perform a new integral.

- $\left\langle\alpha^{\prime}, L^{\prime}=2, M^{\prime}=2\right| P_{x}^{2}+P_{y}^{2}-2 P_{z}^{2}|\alpha, L=4, M=2\rangle$
- $\left\langle\alpha^{\prime}, L^{\prime}=2, M^{\prime}=2\right| P_{x}^{2}+P_{y}^{2}|\alpha, L=4, M=2\rangle$
- $\left\langle\alpha^{\prime}, L^{\prime}=2, M^{\prime}=0\right| P_{x} P_{y}|\alpha, L=4, M=2\rangle$
- $\left\langle\alpha^{\prime}, L^{\prime}=2, M^{\prime}=0\right| P_{x}^{2}+P_{y}^{2}-2 P_{z}^{2}|\alpha, L=2, M=0\rangle$


## Irreducible Tensor Operators

The irreducible tensor operators are defined as

$$
\begin{equation*}
T_{q}^{k} \propto r^{k} Y_{k, q} \tag{1}
\end{equation*}
$$

where $\boldsymbol{k}$ is the rank of the tensor and $\boldsymbol{q}$ is its projection.
Using this equation you can express polynomial operators as linear combinations of the irreducible tensor operators as they transform similarly under rotations. For example, the position operator $\boldsymbol{x}$ can be written in spherical coordinates as

$$
\begin{equation*}
x=r \sin \theta \cos \phi=\frac{1}{2} r \sin \theta\left(e^{i \phi}+e^{-i \phi}\right) \propto r\left(Y_{1,-1}-Y_{1,1}\right) \tag{2}
\end{equation*}
$$

Thus $\boldsymbol{x}$ transforms as $\left(\boldsymbol{T}_{-\mathbf{1}}^{\mathbf{1}}-\boldsymbol{T}_{\mathbf{1}}^{\mathbf{1}}\right)$. The set of operators $\boldsymbol{x} \boldsymbol{y}$ can be written as

$$
\begin{align*}
x y & =r^{2} \sin ^{2} \theta \cos \phi \sin \phi \\
& =\frac{1}{4 i} r^{2} \sin ^{2} \theta\left(e^{i \phi}+e^{-i \phi}\right)\left(e^{i \phi}-e^{-i \phi}\right)  \tag{3}\\
& =\frac{1}{4 i} r^{2} \sin ^{2} \theta\left(e^{2 i \phi}+e^{-2 i \phi}\right) \\
& \propto r^{2}\left(Y_{2,2}+Y_{2,-1}\right)
\end{align*}
$$

which transforms as $\left(\boldsymbol{T}_{\mathbf{2}}^{\mathbf{2}}+\boldsymbol{T}_{-2}^{2}\right)$. The operator $\boldsymbol{x}^{\mathbf{2}}+\boldsymbol{y}^{\mathbf{2}}$ can written as

$$
\begin{align*}
x^{2}+y^{2} & =r^{2} \sin ^{2} \theta\left(\cos ^{2} \phi+\sin ^{2} \phi\right) \\
& =r^{2} \sin ^{2} \theta \\
& =r^{2}\left(1-\cos ^{2} \theta\right)  \tag{4}\\
& =\frac{1}{3} r^{2}\left(2-\left(3 \cos ^{2} \theta-1\right)\right) \\
& \propto r^{2}\left(\frac{2}{3} Y_{0,0}-\frac{1}{3} Y_{2,0}\right)
\end{align*}
$$

which transforms as $\frac{2}{3} r^{2} T_{0}^{0}-\frac{1}{3} T_{0}^{2}$. The last relevant operator is $x^{2}+y^{2}-2 z^{2}$, which can be expressed as

$$
\begin{align*}
x^{2}+y^{2}-2 z^{2} & =r^{2}\left(\sin ^{2} \theta\left(\cos ^{2} \phi+\sin ^{2} \phi\right)-2 \cos ^{2} \theta\right) \\
& =r^{2}\left(\sin ^{2} \theta-2 \cos ^{2} \theta\right) \\
& =r^{2}\left(1-\cos ^{2} \theta-2 \cos ^{2} \theta\right)  \tag{5}\\
& =-r^{2}\left(3 \cos ^{2} \theta-1\right) \\
& \propto r^{2} Y_{2,0}
\end{align*}
$$

which transforms as $\boldsymbol{T}_{\mathbf{0}}^{\mathbf{2}}$.
Operators that transform similarly under rotation to $\boldsymbol{x}, \boldsymbol{y}$, and $\boldsymbol{z}\left(\boldsymbol{P}_{\boldsymbol{i}}, \boldsymbol{L}_{\boldsymbol{i}}, \boldsymbol{J}_{\boldsymbol{i}}\right.$, etc. $)$ would transform as the same irreducible tensor operators $\boldsymbol{T}_{\boldsymbol{q}}^{\boldsymbol{k}}$.

## Wigner-Eckart Theorem

The general expression of the Wigner-Eckart theorem is

$$
\begin{equation*}
\left\langle\alpha^{\prime}, L^{\prime}, M^{\prime}\right| T_{q}^{k}|\alpha, L, M\rangle=\left\langle k, q, L^{\prime}, M^{\prime} \mid L, M\right\rangle \frac{\left\langle\alpha^{\prime}, L^{\prime}\left\|T^{(k)}\right\| \alpha, L\right\rangle}{\sqrt{2 L^{\prime}+1}} \tag{6}
\end{equation*}
$$

The double bars in the reduced matrix operator indicate the independence of the matrix element on the projection $\boldsymbol{M}$. The usefulness of this theorem is that if we calculate the matrix element $\boldsymbol{\mathcal { M }}$ for one combination of $\boldsymbol{M}^{\prime}, \boldsymbol{M}$ and $\boldsymbol{q}$ and generate the reduced matrix element, then we can use it to express all other matrix elements with the same values of $\boldsymbol{L}^{\prime}, \boldsymbol{L}$ and $\boldsymbol{k}$ in terms of the reduced matrix element and the Clebsch-Gordan coefficient.
The selection rules for the matrix element not to be zero are

$$
\begin{equation*}
\Delta M=M^{\prime}-M=q \quad \text { and } \quad|L-k| \leq L^{\prime} \leq L+\boldsymbol{k} \tag{7}
\end{equation*}
$$

With all these tools now in our toolbox we can proceed with answering the questions.

## Solution

(i) We can use the selection rules in (7) to determine which matrix elements are zero.

- $\left\langle\alpha^{\prime}, L^{\prime}=2, M^{\prime}=1\right| P_{x}^{2}+P_{y}^{2}|\alpha, L=4, M=3\rangle$

As shown in (4) the operator $\boldsymbol{P}_{\boldsymbol{x}}^{2}+\boldsymbol{P}_{\boldsymbol{y}}^{2}$ transforms as $\frac{2}{3} r^{2} \boldsymbol{T}_{0}^{0}-\frac{1}{3} \boldsymbol{T}_{0}^{2}$. The selection rules require that the non zero matrix elements would correspond to the transition between states with

$$
\Delta M=q=0 \quad \text { and } \quad \Delta L=k=\mathbf{2} \text { or } \mathbf{0}
$$

which is not the case for this matrix element, since we can see that

$$
M^{\prime}-M=-2 \quad \text { and } \quad\left|L^{\prime}-L\right|=2
$$

- $\left\langle\alpha^{\prime}, L^{\prime}=2, M^{\prime}=1\right| P_{x} P_{y}|\alpha, L=4, M=1\rangle$

As shown in (3), the operator $\boldsymbol{P}_{\boldsymbol{x}} \boldsymbol{P}_{\boldsymbol{y}}$ transforms as $\boldsymbol{T}_{\mathbf{2}}^{\mathbf{2}}+\boldsymbol{T}_{-\mathbf{2}}^{\mathbf{2}}$. Thus, this matrix element is zero because $\boldsymbol{\Delta M}=\mathbf{0} \neq \pm \mathbf{2}$

- $\left\langle\alpha^{\prime}, L^{\prime}=2, M^{\prime}=1\right| \epsilon_{i j k} J_{i} R_{j} P_{k}|\alpha, L=2, M=1\rangle$

In this case, we can see that this operator is of rank 0 . This can be seen by noticing that all three indices, $i, j$ and $k$ are bound (they appear more than once). Since there are no free indices, then this is a rank zero operator, hence a scalar. From our set of irreducible tensor operators, the one which is scalar is $\boldsymbol{T}_{\mathbf{0}}^{\mathbf{0}}$, which transforms as $\boldsymbol{Y}_{\mathbf{0}, \mathbf{0}}=\frac{\mathbf{1}}{\sqrt{4 \boldsymbol{\pi}}}$. Since $\boldsymbol{\Delta} \boldsymbol{L}=\boldsymbol{\Delta} \boldsymbol{M}=\mathbf{0}$ then this is a non zero matrix element.

- $\left\langle\alpha^{\prime}, L^{\prime}=2, M^{\prime}=1\right| P_{x}|\alpha, L=4, M=3\rangle$

As shown in (2), the operator $\boldsymbol{P}_{\boldsymbol{x}}$ transforms as $\boldsymbol{T}_{\mathbf{1}}^{\mathbf{1}}+\boldsymbol{T}_{-\mathbf{1}}^{\mathbf{1}}$. Thus, this matrix element is zero because $\Delta M=\mathbf{- 2} \neq \pm \mathbf{1}$.
(ii) $\mathcal{M}=\left\langle\alpha^{\prime}, L^{\prime}=2, M^{\prime}=0\right| P_{x}^{2}+P_{y}^{2}-2 P_{z}^{2}|\alpha, L=4, M=0\rangle$

As shown in (5), $\boldsymbol{P}_{\boldsymbol{x}}^{\mathbf{2}}+\boldsymbol{P}_{\boldsymbol{y}}^{\mathbf{2}}-\mathbf{2} \boldsymbol{P}_{\boldsymbol{z}}^{\mathbf{2}}$ transforms as $\boldsymbol{T}_{\mathbf{0}}^{\mathbf{2}}$. According to the Wigner-Eckart Theorem (6), we know we can express all matrix elements with $\boldsymbol{L}^{\prime}=\mathbf{2}, \boldsymbol{L}=\mathbf{4}, \boldsymbol{k}=\mathbf{2}$ in terms of $\mathcal{M}$ and the Clebsch-Gordan coefficients.

- $\left\langle\alpha^{\prime}, L^{\prime}=2, M^{\prime}=2\right| P_{x}^{2}+P_{y}^{2}-2 P_{z}^{2}|\alpha, L=4, M=2\rangle$

Again, as shown in (5), $\boldsymbol{P}_{\boldsymbol{x}}^{\mathbf{2}}+\boldsymbol{P}_{\boldsymbol{y}}^{\mathbf{2}}-\mathbf{2} \boldsymbol{P}_{\boldsymbol{z}}^{\mathbf{2}}$ transforms as $\boldsymbol{T}_{\mathbf{0}}^{\mathbf{2}}$ and this is a non zero matrix element, because $\boldsymbol{\Delta M} \boldsymbol{M}=\mathbf{0}=\boldsymbol{q}$. Since $\boldsymbol{L}^{\prime}=\mathbf{2}, \boldsymbol{L}=\mathbf{4}$, and $\boldsymbol{k}=\mathbf{2}$ then we can express this in terms of $\boldsymbol{\mathcal { M }}$ and the Clebsch-Gordan coefficients.
$\bullet\left\langle\alpha^{\prime}, L^{\prime}=2, M^{\prime}=2\right| P_{x}^{2}+P_{y}^{2}|\alpha, L=4, M=2\rangle$
As shown in (4) this operator transforms as a linear combination of $\boldsymbol{T}_{\mathbf{0}}^{\mathbf{0}}$ and $\boldsymbol{T}_{\mathbf{0}}^{\mathbf{2}}$. This is a non zero matrix element, because $\boldsymbol{\Delta M}=\mathbf{0}=\boldsymbol{q}$, and again, since $\boldsymbol{L}^{\prime}=\mathbf{2}, \boldsymbol{L}=$ $\mathbf{4}$, and $\boldsymbol{k}=\mathbf{2}$ then we can express this in terms of $\boldsymbol{\mathcal { M }}$ and the Clebsch-Gordan coefficients.

- $\left\langle\alpha^{\prime}, L^{\prime}=2, M^{\prime}=0\right| P_{x} P_{y}|\alpha, L=4, M=2\rangle$

In this case, as shown in (3) the operator transforms as $\boldsymbol{T}_{ \pm 2}^{2}$ and the matrix is non zero because $\boldsymbol{\Delta M}=\mathbf{- 2}=\boldsymbol{q}$ from the $\boldsymbol{T}_{-\mathbf{2}}^{\mathbf{2}}$ operator. Again, since $\boldsymbol{L}^{\prime}=\mathbf{2}, \boldsymbol{L}=\mathbf{4}$, and $\boldsymbol{k}=$ 2 then we can express this matrix element in terms of $\boldsymbol{\mathcal { M }}$ and the Clebsch-Gordan coefficients. However in this case, since it is not the same irreducible operator $T_{0}^{2}$ in both $\boldsymbol{\mathcal { M }}$ and our matrix element, then in our calculation we should take into account the ratio of the constant factors in front of each operator $\boldsymbol{T}_{\boldsymbol{q}}^{\boldsymbol{k}}$, because in this case they will not cancel out.

- $\left\langle\alpha^{\prime}, L^{\prime}=2, M^{\prime}=0\right| P_{x}^{2}+P_{y}^{2}-2 P_{z}^{2}|\alpha, L=2, M=0\rangle$

In this case we can see that $\boldsymbol{L}^{\prime}=\mathbf{2}, \boldsymbol{L}=\mathbf{2}$, and $\boldsymbol{k}=\mathbf{0}$. Hence we can't express this from our matrix element $\boldsymbol{\mathcal { M }}$.

