

# Chapter 7 Problem: Differential Solid Angle and Structure Function

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**Problem** Suppose that the differential scattering angle  $\frac{d\sigma}{d\Omega}$  for a point-like scatterer is  $\alpha$ , independent of scattering angle. Now suppose we have  $N^3 \gg 1$  of these scatterers arranged in a 3-dimensional cubic lattice with spacing  $a$  and side length  $Na$ . Consider a high energy plane wave incident with wavevector  $\vec{k}_i = k\hat{z}$ . Define  $\vec{q} \equiv \vec{k}_i - \vec{k}_f = k[(1 - \cos\theta_s)\hat{z} - \sin\theta_s \cos\phi_s\hat{x} - \sin\theta_s \sin\phi_s\hat{y}]$  where  $\theta_s$  and  $\phi_s$  are the scattering angles.

- What is  $\frac{d\sigma}{d\Omega}$  in terms of  $\alpha$ ,  $N$ ,  $k$ ,  $a$ , and  $\vec{q}$ ?
- Find the condition for  $\vec{q}$  that *maximizes* the differential cross section.
- In the limit that  $N \rightarrow \infty$ , find the condition for  $\vec{q}$  that *minimizes*  $\frac{d\sigma}{d\Omega}$ .
- Repeat parts **a–c** but with a lattice spacing of  $a$  (and side length of  $Na$ ) in the  $\hat{x}$  and  $\hat{y}$  directions and a spacing of  $2a$  (and side length of  $2Na$ ) in the  $\hat{z}$  direction.

## Relevant Equations

$$\frac{d\sigma}{d\Omega} = \left( \frac{d\sigma}{d\Omega} \right)_{\text{point}} \tilde{S}(\vec{q}) \quad (1)$$

$$\tilde{S}(\vec{q}) = \frac{1}{N} \left| \sum_{\vec{a}} e^{i\vec{q}\cdot\vec{a}} \right|^2 \quad (2)$$

## Solution

a) We use Eq. 2 to find the structure function,

$$\begin{aligned}
 \sum_{\vec{a}} e^{i\vec{q}\cdot\vec{a}} &= \sum_{n_x, n_y, n_z=0}^N e^{i\vec{q}\cdot a(n_x\hat{x}+n_y\hat{y}+n_z\hat{z})} \\
 &= \sum_{n_x, n_y, n_z=0}^N e^{iq_x a n_x} e^{iq_y a n_y} e^{iq_z a n_z} \\
 &= \prod_{\hat{u} \in \{\hat{x}, \hat{y}, \hat{z}\}} \sum_{n=0}^N (e^{iq_u a})^n \\
 \implies \tilde{S}(\vec{q}) &= \frac{1}{N^3} \left| \prod_{\hat{u} \in \{\hat{x}, \hat{y}, \hat{z}\}} \sum_{n=0}^N (e^{iq_u a})^n \right|^2
 \end{aligned}$$

Then we plug this into Eq. 1.

$$\boxed{\frac{d\sigma}{d\Omega} = \frac{\alpha}{N^3} \left| \prod_{\hat{u} \in \{\hat{x}, \hat{y}, \hat{z}\}} \sum_{n=0}^N (e^{iq_u a})^n \right|^2}$$

b) To maximize  $\frac{d\sigma}{d\Omega}$  we note that the maximum value of each term in the summations is 1, which occurs when  $q_u a = 2j\pi$  where  $j \in \mathbb{Z}$ . So, the maximum occurs when this is true for each  $\hat{u}$ ,

$$\boxed{\begin{cases} q_x a = 2r\pi \\ q_y a = 2s\pi \text{ where } r, s, t \in \mathbb{Z} \\ q_z a = 2t\pi \end{cases}}$$

c) To minimize  $\frac{d\sigma}{d\Omega}$  we note that each individual term in the summations must have  $|(e^{iq_u a})^n|^2 = 1$ . But, the phases of each term will only align when  $e^{iq_u a} = 1$ , otherwise the  $(\cdot)^n$  will rotate the phase by  $q_u a$  for each successive  $n$ . This heuristic explanation shows that the sum will always be bounded (but may not necessarily converge) so long as  $e^{iq_u a} \neq 1$  for some  $q_u$ . Therefore, as  $N \rightarrow \infty$ ,  $\frac{d\sigma}{d\Omega} \rightarrow 0$  when

$$\boxed{\begin{cases} q_x a \neq 2r\pi \\ q_y a \neq 2s\pi \text{ for all } r, s, t \in \mathbb{Z} \\ q_z a \neq 2t\pi \end{cases}}$$

d) It is not necessary to work the entire problem again. We can see that replacing the spacing on the  $\hat{z}$  axis is equivalent to replacing  $n_z$  with  $2n_z$ , and as such all  $q_z$  are replaced with  $2q_z$  in the preceding parts.

$$\frac{d\sigma}{d\Omega} = \frac{\alpha}{N^3} \left| \sum_{n=0}^N (e^{iq_x a})^n \sum_{n=0}^N (e^{iq_y a})^n \sum_{n=0}^N (e^{2iq_z a})^n \right|^2$$

Maximized when  $\begin{cases} q_x a = 2r\pi \\ q_y a = 2s\pi \text{ where } r, s, t \in \mathbb{Z} \\ q_z a = t\pi \end{cases}$

Minimized when  $\begin{cases} q_x a \neq 2r\pi \\ q_y a \neq 2s\pi \text{ for all } r, s, t \in \mathbb{Z} \\ q_z a \neq t\pi \end{cases}$