

Planetoid

$$(a) \quad \vec{\nabla} \cdot \vec{g} = -4\pi G \rho$$

$$\begin{aligned} \rho &= -\frac{1}{4\pi G} \vec{\nabla} \cdot \vec{g} = -\frac{1}{4\pi G} \frac{1}{r^2} \frac{d}{dr} \left[ \left( -\frac{g_0}{1-\alpha} \right) \frac{r^3}{R} \left( 1 - \alpha \frac{r}{R} \right) \right] \\ &= \frac{1}{4\pi G} \frac{g_0}{1-\alpha} \frac{1}{R} \left[ 3 - 4\alpha \frac{r}{R} \right] \end{aligned}$$

Since  $\rho \geq 0$ , we must have  $3 - 4\alpha \frac{r}{R} \geq 0$

$$3 \geq 4\alpha \frac{r}{R}$$

↑  
worst situation  
for  $r=R$

Conclusion  $\alpha \leq \frac{3}{4}$ .

$$\begin{aligned} (b) \quad M &= \int \rho dV = 4\pi \int_0^R dr \, r^2 \frac{1}{4\pi G R} \frac{g_0}{1-\alpha} \left( 3 - 4\alpha \frac{r}{R} \right) \\ &= \frac{1}{G R} \frac{g_0}{1-\alpha} \int_0^R dr \left( 3r^2 - \frac{4\alpha}{R} r^3 \right) \\ &= \frac{1}{G R} \frac{g_0}{1-\alpha} \cdot \left[ 3 \frac{r^3}{3} - \frac{4\alpha}{R} \frac{r^4}{4} \right] \Big|_0^R \\ &= \frac{1}{G} \frac{g_0}{1-\alpha} R^2 [1-\alpha] = \frac{g_0 R^2}{G} \end{aligned}$$

$$(c) \quad 4\pi R^2 g(R) = -4\pi G M \Rightarrow M = -\frac{R^2}{G} (-g_0) = \frac{g_0 R^2}{G} \text{ or.}$$

Skater

$$(a) \quad l = r_i m v_i = 55 \text{ kg} \times 3.1 \frac{\text{m}}{\text{s}} \times 3.4 \text{ m} \\ = 579.7 \text{ kg m}^2/\text{s}$$

$$(b) \quad l = r_f m v_f$$

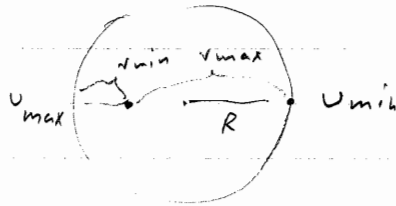
$$579.7 = 1.7 \text{ m} \times 55 \text{ kg} \times v_f$$

$$v_f = \frac{l}{1.7 \text{ m} \times 55 \text{ kg}} = 6.2 \frac{\text{m}}{\text{s}}$$

$$(c) \quad W = K_f - K_i = \frac{m v_f^2}{2} - \frac{m v_i^2}{2} \\ = \frac{55}{2} (6.2^2 - 3.1^2) = 793 \text{ J}$$

$$(d) \quad \frac{l^2}{2 m r_f^2} - \frac{l^2}{2 m r_i^2} = \frac{\frac{l^2}{m r_f^2} v_f^2}{2 m r_f^2} - \frac{\frac{l^2}{m r_i^2} v_i^2}{2 m r_i^2} \\ = \frac{m v_f^2}{2} - \frac{m v_i^2}{2} = W$$

## Circular Orbit



$$l = v_{max} m r_{min} = v_{min} m r_{max}$$

$$l = m r^2 \dot{\theta} \Rightarrow \frac{l}{m} = r^2 \dot{\theta}$$

$$\text{const} = \frac{1}{2} \frac{l}{m} = \frac{1}{2} v^2 \dot{\theta} = \frac{dA}{dt} = \frac{A}{T}$$

$$T = \frac{2Am}{l} = \frac{2\pi R^2 m}{l}$$

$$l = m v_{max} r_{min} = m v_{min} (2R - r_{min})$$

$$v_{max} r_{min} = v_{min} (2R - r_{min})$$

$$\frac{v_{max}}{v_{min}} r_{min} = 2R - r_{min}$$

$$\left(1 + \frac{v_{max}}{v_{min}}\right) r_{min} = 2R \Rightarrow r_{min} = \frac{2v_{min}R}{v_{min} + v_{max}}$$

$$l = m v_{max} r_{min} = m \frac{2v_{max} v_{min} R}{v_{min} + v_{max}}$$

$$T = \frac{2\pi R^2 m}{m \frac{2v_{max} v_{min} R}{v_{min} + v_{max}}} = \frac{\pi R (v_{min} + v_{max})}{v_{min} \cdot v_{max}}$$

## Stationary satellite

(a)  $T = 24h$

$$\frac{mv^2}{r} = \frac{mMG}{r^2}$$

$$v = \frac{2\pi r}{T}$$

$$\frac{1}{r} \left( \frac{2\pi r}{T} \right)^2 = \frac{MG}{r^2}$$

$$\frac{4\pi^2 r}{T^2} = \frac{MG}{r^2}$$

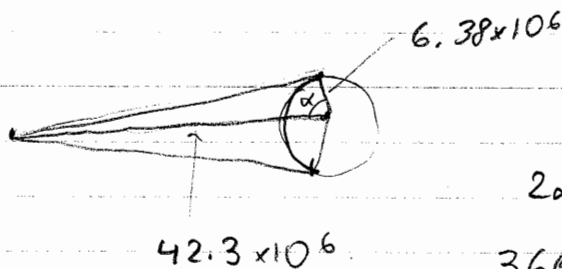
$$\frac{4\pi^2 r}{T^2} = \frac{gR^2}{r^2}$$

$$r^3 = \frac{gR^2 T^2}{4\pi^2} = \left( \frac{RT}{2\pi} \right)^2 g$$

$$r = \sqrt[3]{\left( \frac{RT}{2\pi} \right)^2 g} = \sqrt[3]{9.81 \frac{m}{s^2} \left[ \frac{24 \times 3600 s \times 6.38 \times 10^6 m}{2\pi} \right]^2}$$

$$r = 4.23 \times 10^7 m$$

(b)



$$\cos \alpha = \frac{R}{r} \quad \alpha = \cos^{-1} \frac{6.38}{42.3} = 81.3^\circ$$

$$2\alpha = 162.7^\circ$$

$$\frac{360^\circ}{2\alpha} = 2.21 \Rightarrow 3 \text{ satellites needed}$$

## Inverse-Cube Law

$$\frac{m v^2}{r} = F = G \frac{mM}{r^3}$$

$$\frac{(2\pi r)^2}{r T^2} = G \frac{M}{r^3}$$

$$\frac{4\pi^2 r}{T^2} = G \frac{M}{r^3}$$

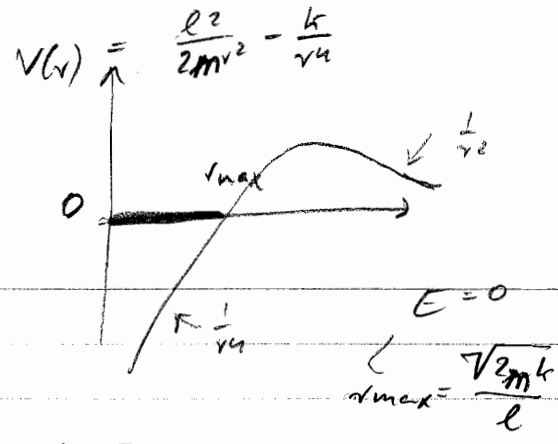
$$T^2 = \frac{4\pi^2 r^4}{GM}$$

$$T = \frac{2\pi r^2}{\sqrt{GM}}$$

i. e.  $T \propto r^2$

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$1/r^4$  potential



$$\Theta = \pm \int \frac{l}{r^2} \frac{dr}{\sqrt{2m \left( \frac{k}{r^4} - \frac{l^2}{2m r^2} \right)}}$$

$$= \pm l \int \frac{dr}{\sqrt{2mk - l^2 r^2}} = \pm \frac{l}{\sqrt{2mk}} \int \frac{dr}{\sqrt{1 - \frac{l^2 r^2}{2mk}}}$$

$$y = \frac{lr}{\sqrt{2mk}} = \pm \int \frac{dy}{\sqrt{1 - y^2}}$$

$$y = \sin \alpha \quad dy = \cos \alpha \, d\alpha$$

$$\sqrt{1 - y^2} = \cos \alpha$$

$$\Theta = \pm \alpha + \text{const}$$

$$\alpha = \sin^{-1} \frac{lr}{\sqrt{2mk}}$$

$$\Theta = \pm \sin^{-1} \frac{lr}{\sqrt{2mk}} + \text{const}$$

$$\frac{lr}{\sqrt{2mk}} = \sin(\pm \Theta + \text{const})$$

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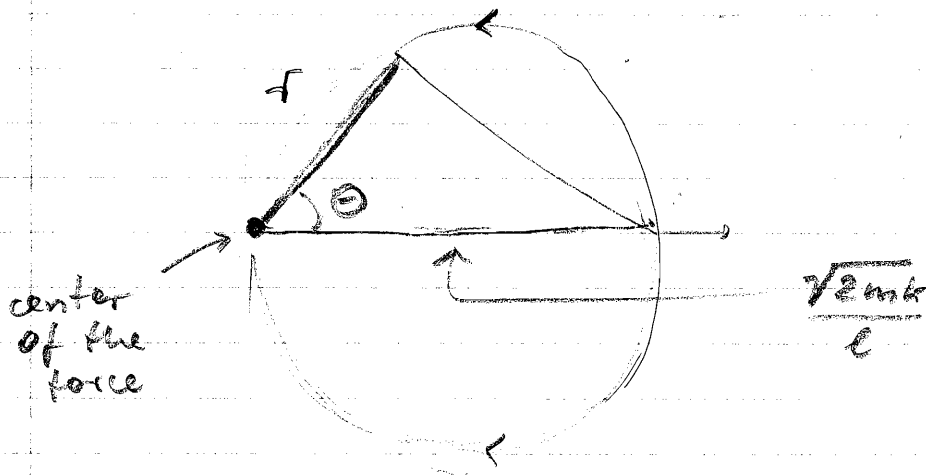
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$1/r^4$  potential

$$r = \frac{\sqrt{2mk}}{l} \sin(\pm\theta + \text{const})$$

Range of  $\theta$ , for which  $r$  may be maintained positive, is  $\pi$ .



For this situation,  $\text{const} = \frac{\pi}{2}$

$$r = \frac{\sqrt{2mk}}{l} \cos \theta$$